

# Semi-Invariant Submanifolds of Riemannian Product Manifold

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**Dedicated to the Memory of Grigorios TSAGAS (1935-2003),  
President of Balkan Society of Geometers (1997-2003)**

## Abstract

In this paper, the geometry of submanifolds of a Riemannian product manifold is studied. Fundamental properties of these submanifolds are investigated such as integrability of distributions, totally umbilical semi-invariant submanifold. Finally, necessary and sufficient conditions are given on a semi-invariant submanifold of a Riemannian product manifold to be a locally Riemannian manifold.

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**Key words:** Riemannian product manifold, totally umbilical submanifold, mixed geodesic submanifold, constant sectional curved manifold

## 1 Introduction

The geometry of a submanifold  $(M, g)$  of a locally Riemannian product manifold  $(\overline{M}_1 \times \overline{M}_2, \overline{g}_1 \otimes \overline{g}_2)$  was widely studied by many geometers. In particular, K. Matsumoto has proved that  $(M, g)$  is a locally product Riemannian manifold of Riemannian manifolds  $(M_a, g_a)$  and  $(M_b, g_b)$ , if it is an invariant submanifold of a Riemannian product manifold  $(\overline{M}_1 \times \overline{M}_2, \overline{g}_1 \otimes \overline{g}_2)$  (see [4]). After then Senlin, Xu., and Yilong, Ni., have updated theorem of Matsumoto and proved that  $M_a \subset \overline{M}_1$  and  $M_b \subset \overline{M}_2$ . Moreover, they have proved that  $(M_a, g_a)$  and  $(M_b, g_b)$  are pseudo-umbilical submanifolds of  $(\overline{M}_1, \overline{g}_1)$  and  $(\overline{M}_2, \overline{g}_2)$ , respectively, if  $(M, g)$  is a pseudo-umbilical submanifold of  $(\overline{M}, \overline{g}) = (\overline{M}_1 \times \overline{M}_2, \overline{g}_1 \otimes \overline{g}_2)$ . They have also demonstrated that  $M$  is isometric to the production of its two totally geodesic submanifolds  $(M_a, g_a)$  and  $(M_b, g_b)$  which are submanifolds of  $(\overline{M}_1, \overline{g}_1)$  and  $(\overline{M}_2, \overline{g}_2)$ , respectively (see [5]).

In this work, we study the geometry of semi-invariant submanifolds of a Riemannian manifold and proved that a semi-invariant submanifold of a Riemannian product manifold is a locally Riemannian product manifold iff  $A_{FD^\perp} D = 0$ , which is equivalent to  $\nabla f = 0$ , or  $Bh(X, Y) = 0$  for any  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ . Moreover, necessary and sufficient conditions are given on distributions  $D$  and  $D^\perp$  of

a semi-invariant submanifold  $M$  are integrable. Finally, we show that there exists no totally umbilical semi-invariant submanifold of positively or negatively curved Riemannian product manifold. Also we give an example for semi-invariant submanifold to illustrate the our results.

## 2 Preliminaries

In this section, we give some notations and terminology used throughout this paper. We recall some necessary facts and formulas from the theory of submanifolds. For an arbitrary submanifold  $M$  of a Riemannian manifold  $\bar{M}$ , Gauss and Weingarten formulas are given by

$$(2.1) \quad \bar{\nabla}_X Y = \nabla_X Y + h(X, Y),$$

and

$$(2.2) \quad \bar{\nabla}_X \xi = -A_\xi X + \nabla_X^\perp \xi,$$

respectively, where  $\bar{\nabla}$ ,  $\nabla$  are Levi-Civita connections on the Riemannian manifolds  $\bar{M}$  and its submanifold  $M$ , respectively, and  $X, Y$  are vector fields tangent to  $M$ ,  $\xi$  is a vector field normal to  $M$ ,  $h : TM \times TM \rightarrow TM^\perp$  is the second fundamental form of  $M$ ,  $\nabla^\perp$  is the normal connection in the normal vector bundle  $TM^\perp$ , and  $A_\xi$  is the shape operator of the second quadratic form for a normal vector  $\xi$ . Moreover, we have

$$(2.3) \quad g(A_\xi X, Y) = \bar{g}(h(X, Y), \xi),$$

where the symbols  $\bar{g}$  and  $g$  mean the Riemannian metrics of  $\bar{M}$  and its submanifold  $M$ , respectively.

We denote the Riemannian curvature tensors of the Levi-Civita connections  $\bar{\nabla}$  and  $\nabla$  on  $\bar{M}$  and  $M$  by  $\bar{R}$  and  $R$ , respectively. The Gauss, Codazzi, and Ricci equations are given by

$$(2.4) \quad \begin{aligned} \bar{g}(\bar{R}(X, Y)Z, W) &= \bar{g}(R(X, Y)Z, W) + \bar{g}(h(X, W), h(Y, Z)) \\ &- \bar{g}(h(X, Z), h(Y, W)) \end{aligned}$$

$$(2.5) \quad (\bar{R}(X, Y)Z)^\perp = (\bar{\nabla}_X h)(Y, Z) - (\bar{\nabla}_Y h)(X, Z),$$

$$(2.6) \quad \bar{g}(\bar{R}(X, Y)\xi, \eta) = \bar{g}(\bar{R}^\perp(X, Y)\xi, \eta) - \bar{g}([A_\xi, A_\eta]X, Y)$$

respectively, where the vector fields  $X, Y, Z, W$  are tangent to  $M$ , the vector fields  $\xi$  and  $\eta$  are orthogonal to  $M$ ,  $(\bar{R}(X, Y)Z)^\perp$  denotes the normal of  $\bar{R}(X, Y)Z$  and the derivative  $\bar{\nabla}h$  is defined by

$$(2.7) \quad (\bar{\nabla}_X h)(Y, Z) = (\nabla_X^\perp h)(Y, Z) - h(\nabla_X Y, Z) - h(\nabla_X Z, Y).$$

We recall that  $M$  is called a curvature-invariant submanifold, if it has

$$(2.8) \quad (\overline{R}(X, Y)Z)^\perp = 0,$$

which is equivalent to

$$(\overline{\nabla}_X h)(Y, Z) = (\overline{\nabla}_Y h)(X, Z),$$

for all  $X, Y, Z \in \Gamma(TM)$  [3].

**Definition 2.1** For a submanifold  $M \subseteq \overline{M}$  the mean-curvature vector field  $H$  is defined by the formula

$$(2.9) \quad H = \frac{1}{n} \sum_{i=1}^n h(e_i, e_i),$$

where  $\{e_i\}$  is a local orthonormal basis in  $TM$ . If a submanifold  $M \subseteq \overline{M}$  having one of the conditions

$$h = 0, h(X, Y) = g(X, Y)H, \quad g(h(X, Y), H) = \lambda g(X, Y),$$

$$(2.10) \quad H = 0, \lambda \in C^\infty(M, R),$$

then it is called totally geodesic, totally umbilical, pseudo-umbilical and minimal, respectively [2].

Let  $(\overline{M}_1, \overline{g}_1)$  and  $(\overline{M}_2, \overline{g}_2)$  be Riemannian manifolds with dimensions  $n_1$  and  $n_2$ , respectively. Then  $\overline{M} = \overline{M}_1 \times \overline{M}_2$  is the Riemannian product manifold of Riemannian manifolds  $\overline{M}_1$  and  $\overline{M}_2$ . We denote the projection mappings of  $T(\overline{M}_1 \times \overline{M}_2)$  to  $T\overline{M}_1$  and  $T\overline{M}_2$  by  $\pi_*$  and  $\sigma_*$ , respectively. Then we have

$$(2.11) \quad \pi_* + \sigma_* = I, \pi_*^2 = \pi_*, \sigma_*^2 = \sigma_*, \pi_* \times \sigma_* = \sigma_* \times \pi_* = 0.$$

Then the Riemannian metric of  $\overline{M}_1 \times \overline{M}_2$  is given by

$$(2.12) \quad \overline{g}(X, Y) = \overline{g}_1(\pi_* X, \pi_* Y) + \overline{g}_2(\sigma_* X, \sigma_* Y)$$

for all  $X, Y \in \Gamma(T(\overline{M}_1 \times \overline{M}_2))$ . Set  $F = \pi_* - \sigma_*$ , then we can easily see that  $F^2 = I$ . It follows

$$(2.13) \quad \overline{g}(X, Y) = \overline{g}(FX, FY)$$

for all  $X, Y \in \Gamma(T(\overline{M}_1 \times \overline{M}_2))$ .

By the definition of  $\overline{g}$ ,  $\overline{M}_1$  and  $\overline{M}_2$  are totally geodesic submanifolds of  $\overline{M}_1 \times \overline{M}_2$ . We denote the Levi-Civita connection of  $\overline{M}_1 \times \overline{M}_2$  by  $\overline{\nabla}$ , we can easily see that

$$(2.14) \quad (\overline{\nabla}_X F)Y = 0.$$

for any  $X, Y \in \Gamma(T(\overline{M}_1 \times \overline{M}_2))$ (For the detail, we refer to[5]).

### 3 Semi-invariant submanifold of a Riemannian product manifold

We denote the Riemannian product manifold  $(\overline{M}_1 \times \overline{M}_2, \overline{g}_1 \times \overline{g}_2)$  by  $(\overline{M}, \overline{g})$  throughout this paper.

**Definition 3.1** *let  $M$  be a submanifold of a Riemannian product manifold  $\overline{M}$ . We suppose that  $M$  has two the distributions such as  $D$  and  $D^\perp$  such that  $TM = D \oplus D^\perp$ ,  $F(D) = D$  and  $F(D^\perp) \subset TM^\perp$ . In this case,  $M$  is called semi-invariant submanifold of  $\overline{M}$ .*

In the rest of this paper, we assume that  $M$  semi-invariant submanifold of  $\overline{M}$ . We denote the orthogonal complementary of  $F(D^\perp)$  in  $TM^\perp$  by  $V$ , then we have direct sum

$$TM^\perp = F(D^\perp) \oplus V.$$

We denote the projection mappings of  $TM$  to  $D$  and  $D^\perp$  by  $P$  and  $Q$ , respectively. Then for each  $X$  tangent to  $TM$ , we can write  $FX$  in the following way:

$$(3.1) \quad FX = fX + \omega X,$$

where  $fX = FPX$  and  $\omega X = FQX$  are respectively the tangent part and the normal part of  $FX$ . Also, for each vector field  $\xi$  normal to  $M$ , we put

$$(3.2) \quad F\xi = B\xi + C\xi,$$

where  $B\xi$  and  $C\xi$  are respectively the tangent part and the normal part of  $F\xi$ .

We denote dimensions of the distributions  $D$  and  $D^\perp$  by  $p$  and  $q$ , respectively. Then for  $q = 0$  (resp.  $p = 0$ ) a semi-invariant submanifold becomes an invariant submanifold (resp. an anti-invariant submanifold). A proper semi-invariant submanifold is a semi-invariant submanifold which is neither an invariant submanifold nor an anti-invariant submanifold.

**Example 3.2** *We consider a submanifold  $M$  in  $R^6$  given by the equations:*

$$X_1 = X_6 + \frac{1}{2}(X_3 + X_4)^2, X_2 = X_5.$$

*It is easy check that  $M$  is a semi-invariant submanifold of  $R^6 = R^3 \times R^3$ . Then by direct calculation we obtain*

$$TM = \text{Span}\left\{U_1 = \frac{\partial}{\partial X_2} + \frac{\partial}{\partial X_5}, U_2 = (X_3 + X_4)\frac{\partial}{\partial X_1} + \frac{\partial}{\partial X_3},\right. \\ \left. U_3 = (X_3 + X_4)\frac{\partial}{\partial X_1} + \frac{\partial}{\partial X_4}, U_4 = \frac{\partial}{\partial X_1} + \frac{\partial}{\partial X_6}\right\}$$

and

$$TM^\perp = \text{Span}\left\{\xi_1 = -\frac{\partial}{\partial X_1} + (X_3 + X_4)\frac{\partial}{\partial X_3} + (X_3 + X_4)\frac{\partial}{\partial X_4} + \frac{\partial}{\partial X_6},\right. \\ \left.\xi_2 = \frac{\partial}{\partial X_2} - \frac{\partial}{\partial X_5}\right\},$$

where  $D = \text{Span}\{U_2, U_3, U_4\}$  and  $D^\perp = \text{Span}\{U_1\}$ .

**Definition 3.3** Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$ . Then  $M$  is called mixed-geodesic semi-invariant submanifold if  $h(X, Y) = 0$  for any  $X \in \Gamma(D)$  and  $Y \in \Gamma(D^\perp)$ .

We denote the Levi-Civita connections on  $M$  and  $\overline{M}$  by  $\nabla$  and  $\overline{\nabla}$ , respectively.

**Proposition 3.4** Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$ . Then we have

$$(3.3) \quad A_{FZ}W = -A_{FW}Z,$$

for all  $Z, W \in \Gamma(D^\perp)$

**Proof.** From (2.1), (2.2), (2.14) and (3.1) we have

$$-A_{FZ}X + \nabla_X^\perp FZ = F\nabla_X Z + Fh(X, Z)$$

for any  $X \in \Gamma(TM)$  and  $Z \in \Gamma(D^\perp)$ . Using (2.13) we obtain

$$-\overline{g}(A_{FZ}X, W) = \overline{g}(h(X, Z), FW),$$

for any  $W \in \Gamma(D^\perp)$ . Since  $A$  is self adjoint, from (2.3) we get

$$-\overline{g}(A_{FZ}W, X) = \overline{g}(A_{FW}Z, X),$$

which proves our assertion.

**Lemma 3.5** Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$ . Then we have

$$(3.4) \quad A_\xi FX = A_{F\xi}X$$

for any  $X \in \Gamma(D)$  and  $\xi \in \Gamma(V)$ .

**Proof.** Since  $\overline{\nabla}$  is the Levi-Civita connection, from (2.14) we derive

$$\overline{g}(h(FX, Y), \xi) = -\overline{g}(\overline{\nabla}_Y F\xi, X),$$

for any  $X \in \Gamma(D)$ ,  $Y \in \Gamma(TM)$  and  $\xi \in \Gamma(V)$ . Using (2.2) and (2.3) we get

$$\overline{g}(A_\xi FX, Y) = \overline{g}(A_{F\xi}X, Y).$$

Thus proof is complete.

**Lemma 3.6** Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$ . Then we have

$$(3.5) \quad \nabla_Z^\perp FW - \nabla_W^\perp FZ \in \Gamma(D^\perp),$$

for any  $Z, W \in \Gamma(D^\perp)$ .

**Proof.** From (2.1) and (2.2) we have

$$(3.6) \quad \bar{g}(A_{F\xi}Z, W) = \bar{g}(\nabla_Z^\perp FW, \xi)$$

for any  $W, Z \in \Gamma(D^\perp)$  and  $\xi \in \Gamma(V)$ . Since  $A$  is self adjoint, from (3.6) we get

$$\bar{g}(\nabla_Z^\perp FW - \nabla_W^\perp FZ, \xi) = 0,$$

which gives (3.5).

**Theorem 3.7** *Let  $\bar{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\bar{M}$ . Then  $D^\perp$  is integrable if and only if*

$$(3.7) \quad h(X, W) \in \Gamma(V)$$

for any  $X \in \Gamma(D)$  and  $W \in \Gamma D^\perp$ .

**Proof.** From (2.2), (2.14) and (3.3) we get

$$F[Z, W] = 2A_{FZ}W + \nabla_Z^\perp FW - \nabla_W^\perp FZ$$

for any  $Z \in \Gamma(D^\perp)$ . Thus from (2.3) and (2.13) we derive

$$\bar{g}([Z, W], FX) = 2\bar{g}(h(W, X), FZ).$$

Hence the proof is complete.

**Theorem 3.8** *Let  $\bar{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\bar{M}$ . Then  $D$  is integrable if and only if*

$$(3.8) \quad h(X, FY) = h(Y, FX)$$

for any  $X, Y \in \Gamma(D)$ .

**Proof.** By using (2.1), (2.2), (2.14) and (3.1) we derive

$$\nabla_X FY + h(X, FY) = P\nabla_X Y + \omega\nabla_X Y + Fh(X, Y),$$

where interchanging role of vector fields  $X$  and  $Y$ , we obtain

$$\nabla_Y FX + h(Y, FX) = P\nabla_Y X + \omega\nabla_Y X + Fh(Y, X).$$

Thus we have

$$h(X, FY) - h(FX, Y) = \omega([X, Y]).$$

This completes the proof of the theorem.

**Lemma 3.9** *Let  $\bar{M}$  be a Riemannian product manifold and  $M$  be a mixed-geodesic semi-invariant submanifold of  $\bar{M}$ . Then we have*

$$(3.9) \quad A_{F\xi}X = FA_\xi X$$

for any  $X \in \Gamma(D)$  and  $\xi \in \Gamma(V)$ .

**Proof.** From (2.1) and (2.2) we have

$$\bar{g}(A_{F\xi}X - FA_\xi X, Y) = \bar{g}(A_{F\xi}X, Y) - \bar{g}(A_\xi X, FY)$$

for any  $X \in \Gamma(D)$ ,  $Y \in \Gamma(D^\perp)$  and  $\xi \in \Gamma(V)$ . Since  $M$  is a mixed-geodesic submanifold, we have  $A_{F\xi}X \in \Gamma(D)$ . Thus using the equation (2.3) we obtain

$$\bar{g}(A_{F\xi}X - FA_\xi X, Y) = 0.$$

On the other hand, from (2.3) we get

$$\bar{g}(A_{F\xi}X - FA_\xi X, Z) = \bar{g}(h(X, Z), F\xi) - \bar{g}(h(X, FZ), \xi)$$

for any  $X, Z \in \Gamma(D)$ . Thus from (2.14) we derive

$$\bar{g}(A_{F\xi}X - FA_\xi X, Z) = 0,$$

which proves our assertion.

**Theorem 3.10** *Let  $\bar{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\bar{M}$ . Then  $M$  is a locally Riemannian product manifold if and only if  $A_{FZ}X = 0$  for all  $X \in \Gamma(D)$  and  $Z \in \Gamma(D^\perp)$ .*

**Proof.** Let  $M$  be a semi-invariant submanifold of a Riemannian product manifold  $(\bar{M}, \bar{g})$ . Then from (2.1) and (2.2) we have

$$(3.10) \quad \bar{g}(\nabla_X FY, Z) = \bar{g}(A_{FZ}X, Y)$$

and

$$(3.11) \quad \bar{g}(\nabla_W Z, FX) = -\bar{g}(A_{FZ}X, W)$$

for any  $X, Y \in \Gamma(D)$  and  $Z, W \in \Gamma(D^\perp)$ . Now, we suppose that  $M$  is a locally Riemannian product manifold. Then the distributions  $D$  and  $D^\perp$  are parallel. From (3.10) and (3.11) we have  $A_{FZ}X \in \Gamma(D)$  and  $A_{FZ}X \in \Gamma(D^\perp)$ . Since  $D \cap D^\perp = \{0\}$  we obtain  $A_{FZ}X = 0$ .

Conversely, if  $A_{FZ}X = 0$ , then from (3.10) and (3.11) we have the distributions  $D$  and  $D^\perp$  are integrable and leaves of them are parallel. This completes the proof of the theorem.

**Proposition 3.11** *Any pseudo umbilical proper semi-invariant submanifold of a Riemannian product manifold is a mixed-geodesic submanifold.*

**Proof.** We suppose that  $M$  is a pseudo-umbilical proper semi-invariant submanifold of a Riemannian product manifold  $(\bar{M}, \bar{g})$ . Then we have

$$\bar{g}(h(X, Z), H) = \bar{g}(H, H)g(X, Z) = 0,$$

for all  $X \in \Gamma(D)$  and  $Z \in \Gamma(D^\perp)$ , which implies that  $h(X, Z) = 0$ .

**Theorem 3.12** *Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$ . Then  $M$  is a locally Riemannian product manifold if and only if  $\nabla f = 0$ .*

**Proof.** Let  $M$  be a locally Riemannian product semi-invariant submanifold of  $\overline{M}$ . Then we have  $\nabla_U Y \in \Gamma(D)$  for all  $U \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ . Thus from (2.2) and (3.1) we obtain

$$h(U, FY) = F\nabla_U Y + Bh(U, FY) + Ch(U, FY) - \nabla_U FY$$

for any  $U \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ . Hence we get

$$\begin{aligned} h(U, FY) &= Ch(U, FY) \\ (\nabla_U f)Y &= 0 \\ (3.12) \quad Bh(U, FY) &= 0. \end{aligned}$$

In the similar way, we obtain  $(\nabla_U f)Z = 0$  for any  $Z \in \Gamma(D^\perp)$ .

Conversely, we suppose that  $\nabla f = 0$ . Then we have  $\nabla_X fY = f\nabla_X Y$ , for any  $X, Y \in \Gamma(D)$ . It follows that  $\nabla_X Y \in \Gamma(D)$ . In the similar way  $\nabla_Z W \in \Gamma(D^\perp)$  for any  $Z, W \in \Gamma(D^\perp)$ . Thus  $M$  is a locally Riemannian product manifold.

**Theorem 3.13** *Let  $M$  be a semi-invariant submanifold of a Riemannian product manifold  $\overline{M}$ . Then  $M$  is a locally Riemannian product manifold if and only if  $Bh(X, Y) = 0$  for all  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ .*

**Proof.** We assume that  $M$  is a locally Riemannian product manifold. Then from (3.12) we have  $Bh(X, Y) = 0$  for any  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ .

Conversely, we assume that  $Bh(X, Y) = 0$  for any  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ . Then from (2.1), (2.14), (3.1) and (3.2) we get

$$\nabla_X fY + h(X, FY) = f\nabla_X Y + \omega\nabla_X Y + Bh(X, Y) + Ch(X, Y)$$

for any  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ . Thus we derive  $(\nabla_X f)Y = 0$ , that is,  $\nabla_X Y \in \Gamma(D)$ . On the other hand, making use of (2.1), (2.2), (2.14), (3.1) and (3.2) we obtain

$$-A_{FZ}X + \nabla_X^\perp FZ = f\nabla_X Z + \omega\nabla_X Z + Bh(X, Z) + Ch(X, Z)$$

for any  $X \in \Gamma(TM)$  and  $Z \in \Gamma(D^\perp)$ . Thus we obtain

$$(3.13) \quad -A_{FZ}X = f\nabla_X Z$$

for any  $X \in \Gamma(TM)$  and  $Z \in \Gamma(D^\perp)$ . By the using (2.3), (2.13) and (3.2) we derive

$$\bar{g}(f\nabla_X Z, Y) = -\bar{g}(Ch(X, Y), Z) = 0,$$

for all  $X \in \Gamma(TM)$ ,  $Y \in \Gamma(D)$  and  $Z \in \Gamma(D^\perp)$ . Hence we have  $\nabla_X Z \in \Gamma(D^\perp)$ . Thus proof is complete.

In case  $F(D^\perp) = TM^\perp$ , we can give the following theorem.



**Theorem 3.14** *Let  $\overline{M}$  be a Riemannian product manifold and  $M$  be a semi-invariant submanifold of  $\overline{M}$  such that  $F(D^\perp) = TM^\perp$ . Then  $M$  is a locally Riemannian product manifold if and only if  $h(X, Y) = 0$  for all  $X \in \Gamma(TM)$  and  $Y \in \Gamma(D)$ .*

**Theorem 3.15** *Let  $M$  be a totally umbilical proper semi-invariant submanifold of a Riemannian product manifold  $\overline{M}$ . Then one only of the following assertions are valid:*  
 1)  $\dim D^\perp = 1$   
 2)  $M$  is a totally geodesic submanifold.

**Proof.** We suppose that  $M$  is a totally umbilical submanifold of a Riemannian product manifold  $\overline{M}$ . Then from (2.1) and (2.2) and (3.1) we have

$$-\overline{g}(A_{FW}Z, Z) = \overline{g}(Fh(Z, W), Z)$$

for all  $Z, W \in \Gamma(D^\perp)$ . Since  $M$  is a totally umbilical submanifold, from (2.3) and (2.13) we obtain

$$(3.14) \quad -\overline{g}(Z, Z)\overline{g}(FH, W) = \overline{g}(Z, Z)\overline{g}(FH, Z),$$

where  $H$  is the mean curvature vector field of  $M$  in  $\overline{M}$ . Interchanging role of  $Z$  and  $W$  in (3.14) we get

$$(3.15) \quad -\overline{g}(W, W)\overline{g}(FH, Z) = \overline{g}(W, W)\overline{g}(FH, W).$$

Thus from (3.14) and (3.15) we obtain

$$(3.16) \quad \overline{g}(FH, Z) = \frac{\overline{g}(Z, W)^2}{\|Z\|^2\|W\|^2}\overline{g}(FH, Z).$$

Hence, either  $\overline{g}(FH, Z) = 0$  or  $Z$  and  $W$  are linearly dependent. If  $Z$  and  $W$  are linearly dependent, then  $\dim D^\perp = 1$ .

We suppose that  $\dim D^\perp > 1$ . Then from (3.3) we have

$$A_{FBH}Z = -A_{FZ}BH$$

for any  $Z \in \Gamma(D^\perp)$ . By the using (2.3) we get

$$-\overline{g}(Z, W)\overline{g}(BH, BH) = \overline{g}(BH, W)\overline{g}(H, FZ).$$

Since  $\dim D^\perp > 1$ , we can choose  $W$  orthogonal to  $BH$ . Then  $BH = 0$ , that is,  $H \in \Gamma(V)$ . Now we assume that  $H \neq 0$ . From (2.3) and (3.4) we derive

$$(3.17) \quad \overline{g}(FH, H)\overline{g}(X, Y) = \overline{g}(H, H)\overline{g}(FX, Y)$$

for any  $X \in \Gamma(D)$ . We note that the leaf of  $D$  is an invariant submanifold of Riemannian product manifold  $\overline{M}$ . We denote the leaf of  $D$  by  $N$ . Since  $N$  is an invariant submanifold of  $\overline{M}$ , it is a product manifold. Set  $N = N_1 \times N_2$ . Then we have

$$TN_1 = \{X \in \Gamma(TN) | FX = X\}$$

and

$$TN_2 = \{X \in \Gamma(TN) | FX = -X\}.$$

From (3.17) we obtain

$$\bar{g}(X, FX) = \bar{g}(X, X)$$

for any  $X \in \Gamma(D)$ . Thus for  $X = X_2 \in \Gamma(TN_2)$ , we have

$$-\bar{g}(X_2, X_2) = \bar{g}(X_2, X_2),$$

i.e.,

$$\|X_2\| = 0 \implies X_2 = 0.$$

This is a contradiction.

**Theorem 3.16** *There exists no any totally umbilical proper semi-invariant submanifold of positively or negatively curved Riemannian product manifold  $\bar{M}$ .*

**Proof.** We assume that Riemannian product manifold  $\bar{M}$  has constant sectional curvature  $c \neq 0$  and let  $M$  be a totally umbilical proper semi-invariant submanifold of  $\bar{M}$ . Then from the equations Gauss and Codazzi, we have

$$\begin{aligned} \bar{K}(X, Y, X, Y) &= \bar{K}(X, Y, FX, FY) = -\bar{g}(X, FX)\bar{g}(\nabla_Y^\perp H, FY) \\ \bar{K}(X \wedge Y) &= -\bar{g}(X, FX)\bar{g}(\nabla_Y^\perp H, FY). \end{aligned}$$

Since the vector fields  $X$  and  $FX$  are linearly independent, we can choose  $X$  orthogonal to  $FX$ . In this case, we obtain

$$\bar{K}(X \wedge Y) = 0.$$

This is a contradiction, where  $\bar{K}$  denotes the Riemannian-Christoffel curvature tensor of  $\bar{M}$ .

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