

On constant isotropic submanifold by generalized null cubic

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Abstract. In this paper we shall be concerned with curves in an Lorentzian submanifold M_1 , and give a characterization of each constant isotropic immersion by generalized null cubic with constant curvature on the Lorentzian submanifold.

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1 Introduction

We review fundamental equations in submanifold theory. Let M_1 be an n -dimensional Lorentzian submanifold in an $(n+p)$ -dimensional indefinite-Riemannian manifold \bar{M}_α and $f : M_1 \rightarrow (\bar{M}_\alpha, g)$ be a isometric immersion. Throughout this paper we will identify a vector X of M_1 with a vector $f_*(X)$ of \bar{M}_α . We denote the induced metric on M_1 by the same letter g .

If $\bar{\nabla}$ and ∇ denotes the metric connection of \bar{M}_α and the induced connection on M_1 from g respectively then we have Gauss' formula

$$(1.1) \quad \bar{\nabla}_X Y = \nabla_X Y + h(X, Y),$$

where X and Y are tangent vector fields of M_1 and $h(X, Y)$ is the second fundamental form of the immersion. For a vector field N normal to M_1 , we can write

$$(1.2) \quad \bar{\nabla}_X N = -A^N X + \nabla_X^\perp N,$$

where ∇^\perp is the covariant differentiation with respect to the induced connection in the normal bundle $N(M_1)$, A^N is the shape operator of M_1 and satisfies the relation

$$g(A_N(X), Y) = g(h(X, Y), N).$$

For indefinite-Riemannian manifold we refer to O'Neill [6].

Let $\tilde{\nabla}$ be a covariant differentiation induced on the $T(M_1) \oplus N(M_1)$. The covariant differentiation of the second fundamental form h is denoted by $\tilde{\nabla}h$ which is $N(M_1)$ valued tensor field of type $(0, 3)$. $\tilde{\nabla}h$ is also defined by

$$(1.3) \quad (\tilde{\nabla}_X h)(Y, Z) = \nabla_X^\perp (h(Y, Z)) - h(\nabla_X Y, Z) - h(X, \nabla_X Z).$$

The mean curvature vector field of M_1 is defined by

$$H = \frac{1}{n} \sum_{i=1}^n g(e_i, e_i) h(e_i, e_i),$$

where $\{e_1, \dots, e_n\}$ is an orthonormal frame at each point of M_1 . H is said to be parallel if $\nabla^\perp H = 0$ holds. If the second fundamental form h satisfies

$$h(X, Y) = g(X, Y) H$$

for any tangent vector field X and Y of M_1 , then M_1 is called totally umbilical submanifold. If the second fundamental form vanishes identically on M_1 then M_1 is said to be totally geodesic. A totally umbilical submanifold with the parallel mean curvature vector field is said to be an extrinsic sphere.

An isometric immersion $f : M_1 \rightarrow \bar{M}_\alpha$ is said to be *isotropic* at $p \in M_1$ if $\|h(X, X)\| / \|X\|^2 (= \lambda(p))$ does not depend on the choice of $X \in T_p(M)$. If the immersion is isotropic at every point, then the immersion is said to be isotropic. When the function λ is constant on M_1 , we call M_1 a constant (λ -) isotropic submanifold. Note that totally umbilic immersion is isotropic, but the converse is not true.

There are many examples of isotropic submanifolds which are not totally umbilic in standard spheres [7].

The following is well known [5].

Lemma 1. *Let f be isometric immersion of M into (\bar{M}, g) . Then f is isotropic at $p \in M$ if and only if the second fundamental form h of f satisfies $g(h(u, u), h(u, v)) = 0$ for an orthogonal pair $u, v \in T_p(M)$.*

Theory of isotropic submanifolds is one of the most interesting objects in differential geometry. In particular Maeda in [4] obtained that the following theorem by studying the first curvature of each circle on the Riemannian submanifold.

Theorem 1. *Let M^n be an n -dimensional connected Riemannian submanifold of an $(n+p)$ -dimensional Riemannian manifold \tilde{M}^{n+p} through an isometric immersion f . Then the following are equivalent:*

- (i) M^n is a constant (λ -) isotropic submanifold of \tilde{M}^{n+p} .
- (ii) There exist $K > 0$ satisfying that for each circle γ of curvature K on the submanifold M^n the curve $f \circ \gamma$ in \tilde{M}^{n+p} has constant first curvature K_1 along this curve.

In this paper we are interested in generalized null cubic in an Lorentzian submanifold M_1 and give a characterization that these submanifolds are constant (λ -) isotropic in terms of constant first curvature K_1 along this curve.

The starting point to study Lorentzian submanifold consisting of investigate curves lies on the submanifold. In this sense, circles or helices in semi-Riemannian submanifold has been studied by several authors (see, for example [1], [2], [3]).

Here we recall the definition of circles, helix and generalized null cubic in Lorentzian submanifold.

A regular curve in Lorentzian manifold M_1 is a smooth mapping $\gamma : I \rightarrow M_1$. If $\gamma = \gamma(t)$ is a spacelike or timelike curve, we can reparametrize it such that $g(\dot{\gamma}(t), \dot{\gamma}(t)) =$

ε , where $\varepsilon = +1$ if γ spacelike and $\varepsilon = -1$ if γ is timelike, respectively. We assume that the spacelike or timelike curve $\gamma(t)$ has an arc length parametrization.

Let $\gamma = \gamma(t)$ be a timelike curve in M_1 . By $k_j(t)$, we denote the j -th curvature of γ . If $k_j(t) = 0$ for $j > 2$ and if the principal vector field Y and the binormal vector field Z are spacelike, then we have the following Frenet formulas along γ [2].

$$\begin{aligned}
 (1.4) \quad & \dot{\gamma}(t) = X \\
 & \nabla_X X = k_1(t) Y \\
 & \nabla_X Y = k_1(t) X + k_2(t) Z \\
 & \nabla_X Z = -k_2(t) Y,
 \end{aligned}$$

where ∇ denotes the covariant differentiation in M_1 . A curve γ is called a circle if $k_2(t) = 0$ and $k_1(t)$ is positive constant along γ . If both $k_1(t)$ and $k_2(t)$ are positive constant along γ then γ is called helix.

We consider a null curve in a Lorentzian manifold M_1 . By a Cartan Frame $\{X, Y, Z\}$ of a null curve γ we mean a family of vector fields $X = x(t)$, $Y = Y(t)$, $Z = Z(t)$ along the curve γ satisfying the following conditions

$$\begin{aligned}
 (1.5) \quad & \dot{\gamma}(t) = X, \quad g(X, X) = g(Y, Y) = 0, \\
 & g(X, Y) = -1, \quad g(X, Z) = g(Y, Z) = 0, \quad g(Z, Z) = 1 \\
 & \nabla_X X = k_1(t) Z, \quad \nabla_X Y = k_2(t) Z, \quad \nabla_X Z = k_2(t) X + k_1(t) Y,
 \end{aligned}$$

where $k_1(t)$ and $k_2(t)$ are functions defined along the curve γ . If $k_1(t)$ and $k_2(t)$ are positive along γ then, we call the curve γ a Cartan framed null curve with constant curvatures. On the definition of the Cartan frame of a null curve γ , if $k_2(t) = 0$ then γ is called a generalized null cubic. Moreover if k_1 is constant, then γ is called a generalized null cubic with constant curvature. For any point p of a Lorentzian manifold, any constants k_1 and k_2 , and any Cartan frame $\{X, Y, Z\}$ at p , there exist locally a Cartan framed null curve γ with constant curvatures passing through p with velocity vector $\dot{\gamma}(t) = X(p)$, which satisfies certain conditions.

Abe in [1] showed that, for $\varepsilon_0 = +1$ or -1 ($-\alpha \leq \varepsilon_0 \leq n - \alpha$), every geodesic γ in M_α with $g(\dot{\gamma}, \dot{\gamma}) = \varepsilon_0$ is a circle in \bar{M}_β iff M_α is constant isotropic and $\bar{\nabla}h(X, X, X) = 0$, for any $X \in T_p(M)$.

Ikawa proved that in [2] M_1 is a totally geodesic submanifold in semi-Riemannian manifold \bar{M}_α if every Cartan framed null curve with constant curvatures in M_1 is also a Cartan framed null curve with constant curvature in \bar{M}_α . Moreover, he also obtained that M_1 is a totally geodesic in \bar{M}_α if every generalized null cubic in M_1 is also a generalized null cubic in \bar{M}_α .

2 Main results

Our aim here is to prove the following theorem which is related to the generalized null cubic.

Theorem 2. *Let M_1 be a Lorentzian submanifold of an indefinite-Riemannian manifold \bar{M}_α through an isometric immersion f . Then the following are equivalent.*

- (i) M_1 is a constant $(\lambda-)$ isotropic submanifold of \bar{M}_α .
- (ii) There exist $K > 0$ satisfying that for each generalized null cubic γ of curvature K on the submanifold M_1 , the curve $f \circ \gamma$ in \bar{M}_α has constant first curvature K_1 along this curve.

Proof. (i) \Rightarrow (ii) : Let $f : M_1 \rightarrow \bar{M}_\alpha$ be a $(\lambda-)$ isotropic immersion. In the following , for simplicity we also denote $f \circ \gamma$ by γ .It follows from the equations(1.1)and(1.5)

$$(2.1) \quad \bar{\nabla}_{\dot{\gamma}(t)}\dot{\gamma}(t) = KZ(t) + h(\dot{\gamma}(t), \dot{\gamma}(t)), t \in I.$$

Here $\bar{\nabla}$ is the Riemannian connection of the ambient space \bar{M}_α and I is the some open interval on \mathbb{R} . Then from (2.1) we can see that the first curvature $K_1 = \|\bar{\nabla}_{\dot{\gamma}}\dot{\gamma}(t)\|$ of the curve $f \circ \gamma$ is equal to $\sqrt{K^2 + \lambda^2}$, which is constant on the interval I .

(ii) \Rightarrow (i) : Let $f : M_1 \rightarrow \bar{M}_\alpha$ be a isotropic immersion satisfying the condition (ii). We take a point $p \in M$ and choose an arbitrary orthonormal pair vectors u and $v \in T_p(M)$. Let γ be a generalized null cubic of curvature K on the submanifold M_1 with initial condition that $\gamma(0) = p$, $\dot{\gamma}(0) = u$ and $\nabla_{\dot{\gamma}}\dot{\gamma}(0) = Kv$. By condition (ii) the first curvature $K_1 = \|\bar{\nabla}_{\dot{\gamma}}\dot{\gamma}\|$ of the curve $f \circ \gamma$ is constant, so that the equation (2.1) implies $\|h(\dot{\gamma}, \dot{\gamma})\|$ is constant on I . Hence, denoting by ∇^\perp the connection of the normal bundle of M_1 in \bar{M}_α , from (1.5) we obtain

$$\begin{aligned} 0 &= \frac{d}{dt} \|h(\dot{\gamma}, \dot{\gamma})\|^2 = 2g(\nabla^\perp(h(\dot{\gamma}, \dot{\gamma})), h(\dot{\gamma}, \dot{\gamma})) \\ &= 2g\left(\left(\tilde{\nabla}_{\dot{\gamma}}h\right)(\dot{\gamma}, \dot{\gamma}) + 2h(\nabla_{\dot{\gamma}}\dot{\gamma}, \dot{\gamma}), h(\dot{\gamma}, \dot{\gamma})\right) \\ &= 2g\left(\left(\tilde{\nabla}_{\dot{\gamma}}h\right)(\dot{\gamma}, \dot{\gamma}), h(\dot{\gamma}, \dot{\gamma})\right) + 4Kg(h(Z, \dot{\gamma}), h(\dot{\gamma}, \dot{\gamma})). \end{aligned}$$

by virtue of the equation (1.3). Evaluating this equation at $t = 0$, we obtain

$$(2.2) \quad g\left(\left(\tilde{\nabla}_u h\right)(u, u), h(u, u)\right) + 2Kg(h(u, v), h(u, u)) = 0.$$

On the other hand, for another generalized null cubic $\rho = \rho(t)$ of the same curvature

K on the submanifold M_1 with the initial condition that $\rho(0) = p, \dot{\rho}(0) = u$, and $\nabla_{\dot{\rho}}\dot{\rho}(0) = -Kv$, we have

$$(2.3) \quad g\left(\left(\tilde{\nabla}_u h\right)(u, u), h(u, u)\right) - 2Kg(h(u, v), h(u, u)) = 0$$

which corresponds to equation (2.2). Thus from (2.2) and (2.3) we can see that

$$g(h(u, v), h(u, u)) = 0,$$

for any orthonormal pair of vectors u and v at each point p of M_1 , so that the submanifold M_1 is $(\lambda-)$ isotropic in \bar{M}_α through the isometric immersion f by Lemma 1.1.

Next, we shall show that $\lambda : M_1 \rightarrow \mathbb{R}$ is constant. It follows from (2.2) and (2.3) that

$$g\left(\left(\tilde{\nabla}_u h\right)(u, u), h(u, u)\right) = 0$$

for every unit vector u at each point p of M_1 .

Then for every generalized null cubic τ on the submanifold M_1 we see that $\lambda = \lambda(t)$ is constant along τ . Therefore we obtained that λ is constant on M_1 . \square

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