

# Projective motion in bi-recurrent Finsler space

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**Abstract.** The existence of projective motion in a symmetric Finsler space was developed by F.M.Meher ([1]). The present author has studied affine and projective motions with contra field in the same space ([4]). Recently the author has discussed projective motions in Finsler spaces ([5]). The purpose of this paper is to study projective motion in bi-recurrent Finsler space. The notations of H.Rund [3] are used in the sequel.

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## 1 Introduction

Let us consider an  $n$ -dimensional Finsler space  $F_n$  with the connection parameters  $G_{jk}^i(x, \dot{x})$  which are positively homogeneous functions of degree zero in the directional arguments, where we briefly denote the line-element  $(x, \dot{x}^i)$  by  $(x, \dot{x})$ . By Euler's law, we have

$$(1.1) \quad \dot{x}^h G_{jkh}^i = \dot{x}^h \dot{\partial}_h G_{jk}^i = 0.$$

The covariant derivative, in the sense of Berwald [3], of a tensor field  $X^i$ , is given by

$$(1.2) \quad X_{(h)}^i = \partial_h X^i - \dot{\partial}_k X^i \dot{\partial}_h G^k + X^k G_{kh}^i,$$

where  $G^i(x, \dot{x})$  is positively homogeneous function of degree two in  $\dot{x}^i$  and  $\partial_h = \frac{\partial}{\partial x^h}$ ,  $\dot{\partial}_k = \frac{\partial}{\partial \dot{x}^k}$ . The corresponding curvature tensor field  $H_{jkh}^i$  of  $F_n$  is expressed in the form

$$(1.3) \quad H_{hjk}^i = \partial_k G_{hj}^i - \partial_j G_{hk}^i + G_{hj}^r G_{rk}^i - G_{hk}^r G_{jr}^i + G_{rhh}^i \dot{\partial}_j G^r - G_{rhj}^i \dot{\partial}_k G^r.$$

The curvature tensor  $H_{jkh}^i$  is skew-symmetric in the last two lower indices  $k, h$  and is homogeneous function of degree zero in  $\dot{x}^i$ , hence we have

$$(1.4) \quad H_{jkh}^i = -H_{jhk}^i,$$

$$(1.5) \quad \dot{\partial}_l H_{jkh}^i \dot{x}^l = 0$$

and

$$(1.6) \quad H_{hjk}^i \dot{x}^h = H_{jk}^i.$$

The commutation formulae involving the above curvature tensors are given as

$$(1.7) \quad 2T_{[(h)(k)]}^i = -\dot{\partial}_i T H_{hk}^i$$

and

$$(1.8) \quad 2T_{j[(h)(k)]}^i = -\dot{\partial}_r T_j^i H_{hk}^r - T_r^i H_{jhk}^r + T_j^r H_{rkh}^i,$$

where  $[hk]$  represents skew-symmetric part. In a non-flat Finsler space  $F_n$  if there exists a non-zero vector field  $K_l$  whose components are positively homogeneous functions of degree zero in  $\dot{x}^i$  such that the curvature tensor  $H_{jkh}^i$  satisfies the relation

$$(1.9) \quad H_{jkh(l)}^i = K_l H_{jkh}^i,$$

then it is called a recurrent Finsler space ([2], [6]) Transvection of (1.9) yields

$$(1.10) \quad H_{kh(l)}^i = K_l H_{kh}^i.$$

Also in a non-flat Finsler space  $F_n$  if there exists a non-zero tensor field  $A_{lm}$  such that the curvature tensor  $H_{jkh}^i$  satisfied the relation

$$(1.11) \quad H_{jkh(l)(m)}^i = A_{lm} H_{jkh}^i,$$

where

$$(1.12) \quad A_{lm} = K_{l(m)} + K_l K_m,$$

then it is called a bi-recurrent Finsler space ([7]). The tensor  $A_{lm}$  defined by (1.12) is called recurrence tensor field whereas the non-zero vector  $K_l$  is called recurrence vector field. We denote such a bi-recurrent Finsler space by  $\bar{F}_n$ .

The successive transvections of (1.11) by  $\dot{x}$  yield

$$(1.13) \quad H_{kh(l)(m)}^i = A_{lm} H_{kh}^i,$$

$$(1.14) \quad H_{h(l)(m)}^i = A_{lm} H_h^i.$$

The Lie-derivatives of a tensor  $T_j^i$  and the connection coefficients  $G_{jk}^i$  defined by the infinitesimal transformation

$$(1.15) \quad \bar{x}^i = x^i + \epsilon v^i(x^j)$$

are characterised by [8]

$$(1.16) \quad L_v T_j^i = v^h T_{j(h)}^i - T_j^h v_{(h)}^i + T_h^i v_{(j)}^h + (\dot{\partial}_h T_j^i) v_{(s)}^h \dot{x}^s$$

and

$$(1.17) \quad L_v G_{jk}^i = v_{(j)(k)}^i + H_{jkh}^i v^h + G_{jkh}^i v_{(s)}^h \dot{x}^s,$$

respectively. The commutation formulae with respect to Lie-derivative and other derivatives for any tensor  $T_{jk}^i$  are given by

$$(1.18) \quad (L_v T_{jk(l)}^i) - (L_v T_{jk}^i)_{(l)} = L_v G_{rl}^i T_{jk}^r - L_v G_{jl}^r T_{rk}^i - L_v G_{kl}^r T_{jr}^i - (L_v G_{lp}^r) \dot{x}^p \partial_r T_{jk}^i$$

and

$$(1.19) \quad \dot{\partial}_l (L_v T_{jk}^i) - L_v (\dot{\partial}_l T_{jk}^i) = 0.$$

The Lie-derivative of the curvature tensor  $H_{jkh}^i$  is given in the form

$$(1.20) \quad (L_v G_{jh}^i)_{(k)} - (L_v G_{kh}^i)_{(j)} = L_v H_{hjk}^i + (L_v G_{kl}^r) \dot{x}^l G_{rjh}^i - (L_v G_{jl}^r) \dot{x}^l G_{rkh}^i.$$

## 2 Projective motion in a bi-recurrent Finsler space

The infinitesimal transformation (1.15) defines a projective motion if it transforms a system of geodesics of  $F_n$  into geodesics. A necessary and sufficient condition that the infinitesimal transformation (1.15) defines a projective motion is that [1]

$$(2.1) \quad L_v G_{jk}^i = 2\delta_{(j}^i p_{k)} + \dot{x}^i p_{jk},^1$$

where

$$(2.2) \quad p_k = \dot{\partial}_k p, \quad p_{jk} = \dot{\partial}_j p_k,$$

for some homogeneous scalar function  $p(x, \dot{x})$  of degree one in  $\dot{x}^i$ . For the homogeneity of  $p_k$  and  $p_{jk}$ , they satisfy

$$(2.3) \quad p_k \dot{x}^k = p, \quad p_{jk} \dot{x}^k = 0.$$

**Definition 2.1.** A bi-recurrent Finsler space  $F_n$ , in which the infinitesimal transformation (1.15) defines a projective motion is called projective bi-recurrent Finsler space and briefly denoted by  $P\bar{F}_n$ .

The present author [5] has established that if the infinitesimal transformation (1.15) defines a projective motion then in view of (2.3) and the homogeneity property of the connection coefficients  $G_{jk}^i$ , the Lie-derivative of the curvature tensor  $H_{jkh}^i$  satisfied the relation

$$(2.4) \quad L_v H_{hjk}^i = 2\delta_h^i p_{[j(k)}] + 2\delta_{[j}^i p_{|h|(k)}] + 2\dot{x}^i p_{[j|h|(k)]},$$

where the index with two parallel bars is unaffected when we consider skew-symmetric part.

Transvecting (2.4) by  $\dot{x}^h$  and using the fact  $\dot{x}^k$  remains invariant under covariant and Lie-differentiations, we find

$$(2.5) \quad L_v H_{jk}^i = 2\dot{x}^i p_{[j(k)}] + 2\delta_{[j}^i p_{(k)}],$$

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<sup>1</sup>(jk) represents symmetric part.

in view of (1.6) and (2.3).

Applying Lie-operator to (1.11) and observing (2.4), we obtain

$$(2.6) \quad L_v H_{jkh(l)(m)}^i = L_v A_{lm} H_{jkh}^i + A_{lm} [2\delta_j^i p_{[k(h)}] + 2\delta_{[k}^i p_{j](h)}] \\ + 2\dot{x}^i p_{[k|j|(h)]}$$

Similarly, the Lie-derivative of (1.13) in view of (2.5) yields

$$(2.7) \quad L_v H_{kh(l)(m)}^i = L_v A_{lm} H_{kh}^i + A_{lm} [2\dot{x}^i p_{[k(h)}] + 2\delta_{[k}^i p_{(h)}]].$$

Hence we state

**Theorem 2.1.** *In a bi-recurrent Finsler space  $P\bar{F}_n$ , which admits projective motion, the relations (2.6) and (2.7) hold good.*

When the projective motion becomes an affine motion, the condition  $L_v G_{jk}^i = 0$  is satisfied. If we apply this condition in (2.1), it yields

$$(2.8) \quad \delta_j^i p_k + \delta_k^i p_j + \dot{x}^i p_{jk} = 0.$$

Setting the indices  $i = k$  in the above equation, we get

$$(2.9) \quad (n+1)p_j + \dot{x}^k p_{jk} = 0.$$

Application of (2.3) in the above equation gives

$$(2.10) \quad (n+1)p_j = 0.$$

which implies

$$(2.11) \quad p_j = 0.$$

Conversely, if (2.11) is true, the equation (2.1) reduces to  $L_v G_{jk}^i = 0$ , in view of (2.3). It means  $p_j = 0$  is the necessary and sufficient condition for the infinitesimal transformation (1.15) which defines projective motion to be an affine motion. In that case from the equation (1.6) and (1.20), we get  $L_v H_{jkh}^i = 0$ ,  $L_v H_{jk}^i = 0$  and the equations (2.6) and (2.7) assume the forms

$$(2.12) \quad L_v H_{jkh(l)(m)}^i = L_v A_{lm} H_{jkh}^i$$

and

$$(2.13) \quad L_v H_{kh(l)(m)}^i = L_v A_{lm} H_{kh}^i,$$

respectively. Hence we have

**Theorem 2.2.** *In a projective bi-recurrent Finsler space  $P\bar{F}_n$ , if the projective motion becomes an affine motion, the relations (2.12) and (2.13) are necessarily true.*

Applying the commutation formula (1.19) for  $H_{jkh}^i$ , we find

$$(2.14) \quad \dot{\partial}_l (L_v H_{jkh}^i) = L_v (\dot{\partial}_l H_{jkh}^i).$$

If the projective motion (1.15) becomes an affine motion the equation (2.14) reduces to

$$(2.15) \quad L_v(\dot{\partial}_l H^i_{jkh}) = 0.$$

Using the commutation formula (1.8) for the curvature tensor  $H^i_{jkh}$ , we obtain

$$(2.16) \quad \begin{aligned} 2H^i_{jkh[(l)(m)]} = & -\dot{\partial}_r H^i_{jkh} H^r_{lm} + H^r_{jkh} H^i_{rlm} - H^i_{rkh} H^r_{jlm} \\ & - H^i_{jrh} H^r_{klm} - H^i_{jkr} H^r_{hlm} \end{aligned}$$

Applying Lie-operator to both sides of (2.16) and using (2.15), we get

$$(2.17) \quad L_v H^i_{jkh[(l)(m)]} = 0,$$

since the projective motion becomes an affine motion. In a bi-recurrent Finsler space  $\overline{F}_n$ , in view of (1.11), the equation (2.17) takes the form

$$(2.18) \quad L_v A_{[lm]} = 0,$$

since  $\overline{F}_n$  is non-flat space. Accordingly we have

**Theorem 2.3.** *In a projective bi-recurrent Finsler space  $P\overline{F}_n$ , if the projective motion becomes an affine motion, the recurrence tensor field  $A_{lm}$  satisfies the identity (2.18).*

We notice that in a recurrent Finsler space  $\overline{F}_n$ , if an affine motion is admitted, then the recurrence vector is Lie-invariant, that is  $L_v K_l = 0$ . Commuting (1.13) with respect to the indices  $l, m$  and noting commutation formula (1.8), we obtain

$$(2.19) \quad (A_{lm} - A_{ml})H^i_{kh} = H^i_{kh} H^i_{rlm} - H^r_{lm} H^i_{rkh} - H^i_{rk} H^r_{hlm} - H^i_{hr} H^r_{klm}.$$

Covariant differentiation of (2.19) with respect to  $x^n$  yields

$$(2.20) \quad A_{[lm](n)} = K_n A_{[lm]},$$

in view of (1.9), (1.10) and (2.19). If we observe the fact that  $L_v K_l = 0$  and Theorem 2.3, in the Lie-derivative of (2.20), we obtain

$$(2.21) \quad L_v A_{[lm](n)} = 0,$$

which gives the identity

$$(2.22) \quad L_v A_{[lm](n)} + L_v A_{[mn](l)} + L_v A_{[nl](m)} = 0.$$

Hence we state

**Theorem 2.4.** *In a projective bi-recurrent Finsler space  $P\overline{F}_n$ , if the projective motion becomes an affine motion, the recurrence tensor field  $A_{lm}$  satisfies the identity (2.22).*

### 3 Further discussion

In a projective bi-recurrent Finsler space  $P\bar{F}_n$ , if the vector field  $v^i(x)$  satisfies the relation

$$(3.1) \quad v_{(j)}^i = 0,$$

then the vector field  $v^i(x)$  determines a contra field. In this case, we consider a special infinitesimal transformation

$$(3.2) \quad \bar{x}^i = x^i + \epsilon v^i(x^j), \quad v_{(j)}^i = 0,$$

which defines projective motion in  $P\bar{F}_n$ . Applying equations (2.1) and (3.1) in the equation (1.17), we find

$$(3.3) \quad H_{jkh}^i v^h = 2\delta_{(j}^i p_{k)} + \dot{x}^i p_{jk}.$$

The covariant differentiation of (3.3) twice with respect to  $x^l$  and  $x^m$  yields

$$(3.4) \quad H_{jkh(l)(m)}^i v^h = \delta_j^i p_{k(l)(m)} + \delta_k^i p_{j(l)(m)} + \dot{x}^i p_{jk(l)(m)}$$

in view of (3.1) and the fact that  $\dot{x}^i$  remains invariant under covariant differentiation. From equations (3.3) and (3.4), we conclude

$$(3.5) \quad \delta_j^i [p_{k(l)(m)} - A_{lm} p_k] + \delta_k^i [p_{j(l)(m)} - A_{lm} p_j] + \dot{x}^i [p_{jk(l)(m)} - A_{lm} p_{jk}] = 0$$

by using (1.11). The above equation is only true if

$$(3.6) \quad (a) p_{k(l)(m)} = A_{lm} p_k, \quad (b) p_{jk(l)(m)} = A_{lm} p_{jk},$$

which implies that the scalar function  $p(x, \dot{x})$  is bi-recurrent in  $P\bar{F}_n$ . Hence we have

**Theorem 3.1.** *In a projective bi-recurrent Finsler space  $P\bar{F}_n$ , which admits projective motion, if the vector field  $v^i(x)$  spans a contra field, then the scalar function  $p(x, \dot{x})$  is bi-recurrent.*

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