

On Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold

Brijesh Kumar Gupta, Braj Bhushan Chaturvedi, Mehraj Ahmad Lone

Abstract. The aim of this paper is to study Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold and a holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold.

M.S.C. 2010: 53C25, 53B35.

Key words: Generalised quasi-Einstein manifold; super quasi-Einstein manifold; mixed super quasi-Einstein manifold; pseudo quasi-Einstein manifold.

1 Introduction

An even dimensional differentiable manifold M^n is said to be a Hermitian manifold if a complex structure J of type (1,1) and a pseudo-Riemannian metric g of the manifold satisfy

$$J^2 = -I,$$

and

$$(1.1) \quad g(JX, JY) = g(X, Y),$$

where $X, Y \in \chi(M)$ and $\chi(M)$ is the Lie algebra of vector fields on the manifold. The notion of an Einstein manifold was introduced by Albert Einstein in differential geometry and mathematical physics. An Einstein manifold is a Riemannian or pseudo-Riemannian manifold (M^n, g) ($n \geq 2$) in which the Ricci tensor is a scalar multiple of the Riemannian metric, i.e.,

$$(1.2) \quad S(X, Y) = \alpha g(X, Y),$$

where S denotes the Ricci tensor of the manifold (M^n, g) ($n \geq 2$) and α is a non-zero scalar. An Einstein manifold plays an important role in the study of Riemannian geometry and in the general theory of relativity. From the equation (1.2), we get

$$r = n\alpha.$$

In 2000, M. C. Chaki and R.K. Maity [4] introduced a new type of a non-flat Riemannian manifold, whose non-zero Ricci tensor satisfies

$$(1.3) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y),$$

and they called it a quasi-Einstein manifold, where α and β are scalars such that $\beta \neq 0$ and A is a non-zero 1-form associated with unit vector field ρ defined by $g(X, \rho) = A(X)$, for every vector field X . ρ is also called generator of the manifold. An n -dimensional quasi-Einstein manifold is denoted by $(QE)_n$. The transvection of the equation (1.3) gives $r = \alpha n + \beta$. From the equations (1.1) and (1.3), we can easily write

$$S(X, \rho) = (\alpha + \beta)A(X), \quad S(\rho, \rho) = (\alpha + \beta), \\ g(J\rho, \rho) = 0, \quad S(J\rho, \rho) = 0.$$

A quasi-Einstein manifold came in existence during the study of exact solutions of Einstein fields equations as well as considerations on the quasi-umbilical hypersurfaces of the semi-Euclidean space. The Walker-space time is an example of a quasi-Einstein manifold. Also, a quasi-Einstein manifold can be taken as a model of the perfect fluid space time in general theory of relativity [7].

In 2001, M.C. Chaki [5] introduced the notion of generalized quasi-Einstein manifold. A Riemannian manifold (M^n, g) ($n \geq 2$) is said to be a generalized quasi-Einstein manifold if the non-zero Ricci tensor of type (0,2) satisfies the condition

$$(1.4) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma C(X)C(Y),$$

where α , β and γ are scalars such that $\beta \neq 0$, $\gamma \neq 0$ and A , C are non-vanishing 1-forms associated with two orthogonal unit vectors ρ and μ by

$$(1.5) \quad g(X, \rho) = A(X), \quad g(X, \mu) = C(X), \\ g(\rho, \rho) = g(\mu, \mu) = 1.$$

An n -dimensional generalized quasi-Einstein manifold is denoted by $G(QE)_n$. After the transvection of (1.4), we get

$$r = \alpha n + \beta + \gamma.$$

Then (1.1), (1.4) and (1.5), immediately infer

$$S(X, \rho) = (\alpha + \beta)A(X), \quad S(X, \mu) = (\alpha + \gamma)C(X), \quad S(\mu, \mu) = \alpha + \gamma, \\ S(\rho, \rho) = \alpha + \beta, \quad g(J\rho, \rho) = g(J\mu, \mu) = 0, \quad \text{and} \quad S(J\mu, \mu) = S(J\rho, \rho) = 0.$$

Also, in 2004, M.C. Chaki [6] introduced the notion of super quasi-Einstein manifolds. A Riemannian manifold (M^n, g) ($n \geq 2$) is said to be a super quasi-Einstein manifold if the non-zero Ricci tensor of type (0, 2) satisfies

$$(1.6) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma[A(X)C(Y) + C(X)A(Y)] + \delta D(X, Y),$$

where α , β , γ and δ are non-zero scalars, A , C are non-vanishing 1-forms defined as (1.5) and ρ , μ are orthogonal unit vector fields, D is a symmetric tensor of order (0, 2) with zero trace, which satisfies the condition

$$(1.7) \quad D(X, \rho) = 0,$$

for any vector field X . An n -dimensional super quasi-Einstein manifold is denoted by $S(QE)_n$. From the equations (1.1), (1.5), (1.6) and (1.7), we can easily write

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X) + \gamma C(X), \quad S(X, \mu) = \alpha C(X) + \gamma A(X), \\ S(\mu, \mu) &= \alpha + \delta D(\mu, \mu), \quad S(\rho, \rho) = \alpha + \beta + \delta D(\rho, \rho), \quad g(J\rho, \rho) = g(J\mu, \mu) = 0, \\ S(J\mu, \mu) &= \gamma A(J\mu) + \delta D(J\mu, \mu), \quad S(J\rho, \rho) = \gamma C(J\rho) + \delta D(J\rho, \rho). \end{aligned}$$

In 2009, A. A. Shaikh [17] introduced the notion of pseudo quasi-Einstein manifold. A semi-Riemannian manifold (M^n, g) ($n \geq 2$) is said to be a pseudo quasi-Einstein manifold if the non-zero Ricci tensor of type $(0, 2)$ satisfies the condition

$$(1.8) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \delta D(X, Y),$$

where α , β , and δ are non-zero scalars and A is a non-zero 1-form defined by $g(X, \rho) = A(X)$. ρ denotes the unit vector called the generator of the manifold and D is a symmetric tensor of type $(0, 2)$ with zero trace defined as in (1.7). An n -dimensional pseudo quasi-Einstein manifold is denoted by $P(QE)_n$. From the equations (1.1), (1.5), (1.7) and (1.8), we get

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X), \quad S(\rho, \rho) = \alpha + \beta, \\ g(J\rho, \rho) &= 0 \text{ and } S(J\rho, \rho) = \delta D(J\rho, \rho). \end{aligned}$$

In 2008, A. Bhattacharyya, M. Tarafdar and D. Debnath [2] introduced the notion of mixed super quasi-Einstein manifolds. A non flat Riemannian manifold (M^n, g) ($n \geq 2$) is said to be a mixed super quasi-Einstein manifold if the non-zero Ricci tensor of type $(0, 2)$ satisfies

$$(1.9) \quad \begin{aligned} S(X, Y) &= \alpha g(X, Y) + \beta A(X)A(Y) + \gamma C(X)C(Y) \\ &+ \delta[A(X)C(Y) + C(X)A(Y)] + \eta D(X, Y), \end{aligned}$$

where β , γ , δ and η are non-zero scalars, A , C are non-vanishing 1-forms defined as in (1.5), ρ and μ are orthogonal unit vector fields and D is a symmetric tensor of type $(0, 2)$ with zero trace, which satisfies $D(X, \rho) = 0$. An n -dimensional mixed super quasi-Einstein manifold is denoted by $MS(QE)_n$. From (1.1), (1.5), (1.7) and (1.8), we get

$$(1.10) \quad \begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X) + \delta C(X), \quad S(X, \mu) = (\alpha + \gamma)C(X) + \delta A(X), \\ S(\mu, \mu) &= \alpha + \gamma + \eta D(\mu, \mu), \quad S(\rho, \rho) = \alpha + \beta + \eta D(\rho, \rho), \quad g(J\rho, \rho) = g(J\mu, \mu) = 0, \\ S(J\mu, \mu) &= \delta A(J\mu) + \eta D(J\mu, \mu), \quad S(J\rho, \rho) = \delta C(J\rho) + \eta D(J\rho, \rho). \end{aligned}$$

In 2008, A. A. Shaikh and S. K. Jana [18] introduced the concept of pseudo generalized quasi-Einstein manifold and also verified it by a suitable example. A Riemannian manifold (M^n, g) ($n \geq 2$) is called a pseudo generalized quasi-Einstein manifold if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the condition

$$(1.11) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma C(X)C(Y) + \delta D(X, Y),$$

where β , γ and δ are non-zero scalars, A , C are non-vanishing 1-forms defined as in (1.5), ρ and μ are orthogonal unit vector fields and D is a symmetric tensor of type

$(0, 2)$ with zero trace and satisfies $D(X, \rho) = 0$. Such type of manifold is denoted by $P(GQE)_n$.

Now contracting equation (1.11), we have

$$r = \alpha n + \beta + \gamma + \delta D.$$

From (1.5), (1.7) and (1.11), we infer

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X), & S(X, \mu) &= (\alpha + \gamma)C(X), \\ S(\rho, \rho) &= (\alpha + \beta) + \delta D(\rho, \rho), & S(\mu, \mu) &= (\alpha + \gamma) + \delta D(\mu, \mu), \\ & & g(J\rho, \rho) &= g(J\mu, \mu) = 0, \\ S(J\mu, \mu) &= \delta D(J\mu, \mu), & \text{and } S(J\rho, \rho) &= \delta D(J\rho, \rho). \end{aligned}$$

2 Semi-symmetric and Ricci semi-symmetric manifolds

Let (M^n, g) be a Riemannian manifold and let ∇ be the Levi-Civita connection on (M^n, g) . Then, the Riemannian manifold is said to be locally symmetric if $\nabla R = 0$, where R is the Riemannian curvature tensor of (M^n, g) . Locally symmetric manifolds have been studied by different geometers through different approaches, and different notions have been developed, e.g., the semi-symmetric manifold (see Szabò, [16]), recurrent manifolds (Walker, [21]), conformally recurrent manifold (Adati and Miyazawa [1]).

According to Z. I. Szabò [16], if the manifold M satisfies the condition

$$(R(X, Y).R)(U, V)W = 0, \quad X, Y, U, V, W \in \chi(M)$$

for all vector fields X and Y , then the manifold is called a semi-symmetric manifold. For a $(0, k)$ - tensor field T on M , $k \geq 1$ and a symmetric $(0, 2)$ -tensor field A on M , the $(0, k + 2)$ -tensor fields $R.T$ and $Q(A, T)$ are defined by

$$\begin{aligned} (R.T)(X_1, \dots, X_k; X, Y) &= -T(R(X, Y)X_1, X_2, \dots, X_k) \\ &\quad - \dots - T(X_1, \dots, X_{k-1}, R(X, Y)X_k), \\ Q(A, T)(X_1, \dots, X_k; X, Y) &= -T((X \wedge_A Y)X_1, X_2, \dots, X_k) \\ &\quad - \dots - T(X_1, \dots, X_{k-1}, (X \wedge_A Y)X_k), \end{aligned}$$

where $X \wedge_A Y$ is the endomorphism given by

$$(X \wedge_A Y)Z = A(Y, Z)X - A(X, Z)Y.$$

Definition 2.1. ([8]) A semi-Riemannian manifold is said to be Ricci semi-symmetric if

$$(R(X, Y).S)(Z, W) = -S(R(X, Y)Z, W) - S(Z, R(X, Y)W) = 0,$$

for all $X, Y, Z, W \in \chi(M^n)$.

The above developments allowed several authors to generalize of the notion of quasi-Einstein manifolds. In this process, generalized quasi-Einstein manifolds were studied by Prakasha and Venkatesha [15] and $N(k)$ -quasi Einstein manifolds were

studied in [14, 20]. In 2012, S.K. Hui and R.S. Lemence [13] discussed generalized quasi-Einstein manifolds admitting a W_2 -curvature tensor, and proved that if the W_2 -curvature tensor satisfies $W_2.S = 0$, then either the associated scalars β and γ are equal, or the curvature tensor R satisfies a definite condition. D.G. Prakasha and H. Venkatesha [15] studied some results on generalized quasi-Einstein manifolds, and proved that in generalized quasi-Einstein manifolds, if the conharmonic curvature tensor satisfies $L.S = 0$, then either M is a nearly quasi-Einstein manifold $N(QE)_n$ or the curvature tensor R satisfies a certain condition. We have studied the above developments in quasi-Einstein manifolds $(QE)_n$, generalized quasi-Einstein manifolds $G(QE)_n$, and super quasi-Einstein manifolds, and decided to study Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifolds and holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifolds.

3 Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold

The notion of Bochner curvature tensor was introduced by S. Bochner [3]. The Bochner curvature tensor B is defined by

$$(3.1) \quad \begin{aligned} B(Y, Z, U, V) = & R(Y, Z, U, V) - \frac{1}{2(n+2)} \left\{ S(Y, V)g(Z, U) - S(Y, U)g(Z, V) \right. \\ & + g(Y, V)S(Z, U) - g(Y, U)S(Z, V) + S(JY, V)g(JZ, U) \\ & - S(JY, U)g(JZ, V) + S(JZ, U)g(JY, V) - g(JY, U)S(JZ, V) \\ & \left. - 2S(JY, Z)g(JU, V) - 2g(JY, Z)S(JU, V) \right\} \\ & + \frac{r}{(2n+2)(2n+4)} \left\{ g(Z, U)g(Y, V) - g(Y, U)g(Z, V) \right. \\ & \left. + g(JZ, U)g(JY, V) - g(JY, U)g(JZ, V) - 2g(JY, Z)g(JU, V) \right\}, \end{aligned}$$

where r is the scalar curvature of the manifold.

In a Hermitian manifold the Bochner curvature tensor satisfies the condition

$$(3.2) \quad B(X, Y, U, V) = -B(X, Y, V, U).$$

We introduce the following:

Definition 3.1. A Hermitian manifold is said to be a mixed super quasi-Einstein Hermitian manifold if it satisfies (1.9). Throughout this paper, we denote the mixed super quasi-Einstein Hermitian manifold by $MS(QEH)_n$.

Definition 3.2. An even dimensional Hermitian manifold (M^n, g) is said to be a Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold if the Bochner curvature tensor of the manifold satisfies $B.S = 0$, i.e.,

$$(3.3) \quad (B(X, Y).S)(Z, W) = -S(B(X, Y)Z, W) - S(Z, (B(X, Y)W)) = 0,$$

for all $X, Y, Z, W \in \chi(M^n)$.

If we take a Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold $MS(QEH)_n$, then from the (1.9) and (3.3), we get

$$(3.4) \quad \begin{aligned} & \alpha[B(X, Y, Z, U) + B(X, Y, U, Z)] \\ & + \beta[A(B(X, Y)Z)A(U) + A(Z)A(B(X, Y)U)] \\ & + \gamma[C(B(X, Y)Z)C(U) + C(Z)C(B(X, Y)U)] \\ & + \delta[A(B(X, Y)Z)C(U) + C(B(X, Y)Z)A(U) \\ & + A(Z)C(B(X, Y)U) + C(Z)A(B(X, Y)U)] \\ & + \eta[D(B(X, Y)Z, U) + D(Z, B(X, Y)U)] = 0, \end{aligned}$$

where $g(B(X, Y)U, Z) = B(X, Y, U, Z)$. Now from the (3.2) and (3.4), we infer

$$(3.5) \quad \begin{aligned} & \beta[A(B(X, Y)Z)A(U) + A(Z)A(B(X, Y)U)] \\ & + \gamma[C(B(X, Y)Z)C(U) + C(Z)C(B(X, Y)U)] \\ & + \delta[A(B(X, Y)Z)C(U) + C(B(X, Y)Z)A(U) \\ & + A(Z)C(B(X, Y)U) + C(Z)A(B(X, Y)U)] \\ & + \eta[D(B(X, Y)Z, U) + D(Z, B(X, Y)U)] = 0; \end{aligned}$$

putting $Z = U = \rho$ in (3.5), we get

$$\delta B(X, Y, \rho, \mu) = 0,$$

which implies either $\delta = 0$ or

$$(3.6) \quad B(X, Y, \rho, \mu) = 0.$$

Using (3.6), if $\delta = 0$, from (1.9), we yield

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma C(X)C(Y) + \eta D(X, Y),$$

which is the condition of having a pseudo-generalized quasi-Einstein manifold. Thus we come to the following conclusion:

Theorem 3.1. *A Bochner Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold is either a Bochner Ricci semi-symmetric pseudo generalised quasi-Einstein Hermitian manifold or*

$$B(X, Y, \rho, \mu) = 0.$$

If we take a Bochner flat curvature tensor then from equation (3.1), we have

$$(3.7) \quad \begin{aligned} R(Y, Z, U, V) &= \frac{1}{2(n+2)} \left\{ S(Y, V)g(Z, U) - S(Y, U)g(Z, V) \right. \\ &+ g(Y, V)S(Z, U) - g(Y, U)S(Z, V) + S(JY, V)g(JZ, U) \\ &- S(JY, U)g(JZ, V) + S(JZ, U)g(JY, V) - g(JY, U)S(JZ, V) \\ &\left. - 2S(JY, Z)g(JU, V) - 2g(JY, Z)S(JU, V) \right\} \\ &- \frac{r}{(2n+2)(2n+4)} \left\{ g(Z, U)g(Y, V) - g(Y, U)g(Z, V) \right. \\ &\left. + g(JZ, U)g(JY, V) - g(JY, U)g(JZ, V) - 2g(JY, Z)g(JU, V) \right\}, \end{aligned}$$

Since the manifold satisfies $R(X, Y).S = 0$, we get

$$(3.8) \quad S(R(Y, Z)U, V) + S(U, R(Y, Z)V) = 0.$$

Using (3.7) in (3.8), we infer

$$(3.9) \quad \left\{ \begin{aligned} & S(QY, V)g(Z, U) - g(Y, U)S(QZ, V) + S(QJY, V)g(JZ, U) \\ & - g(JY, U)S(JQZ, V) - 2g(JY, Z)S(JQU, V) \\ & + S(QY, U)g(Z, V) - g(Y, V)S(QZ, U) + S(QJY, U)g(JZ, V) \\ & - g(JY, V)S(JQZ, U) - 2g(JY, Z)S(JQV, U) \end{aligned} \right\} \\ - \frac{r}{(2n+2)} \left\{ \begin{aligned} & g(Z, U)S(Y, V) - g(Y, U)S(Z, V) + g(JZ, U)S(JY, V) \\ & - g(JY, U)S(JZ, V) + g(Z, V)S(Y, U) - g(Y, V)S(Z, U) \\ & + g(JZ, V)S(JY, U) - g(JY, V)S(JZ, U) \end{aligned} \right\} = 0,$$

If we take λ be an eigenvalue of Q and JQ corresponding to the eigenvectors X and JX , then $QX = \lambda X$ and $QJX = \lambda JX$, i.e., $S(X, U) = \lambda g(X, U)$ (where the manifold is not Einstein), and hence

$$(3.10) \quad S(QX, U) = \lambda S(X, U) \quad \text{and} \quad S(QJX, U) = \lambda S(JX, U).$$

Using (3.10) in (3.9), we have

$$(3.11) \quad \left(\lambda - \frac{r}{(2n+2)} \right) \left\{ \begin{aligned} & S(Y, V)g(Z, U) - g(Y, U)S(Z, V) \\ & + S(Y, U)g(Z, V) - g(Y, V)S(Z, U) + S(JY, V)g(JZ, U) \\ & - S(JZ, V)g(JY, U) + S(JY, U)g(JZ, V) - g(JY, V)S(JZ, U) \end{aligned} \right\} = 0,$$

If we take $\lambda \neq \frac{r}{(2n+2)}$, then from (3.11), we obtain

$$\begin{aligned} & S(Y, V)g(Z, U) - g(Y, U)S(Z, V) \\ & + S(Y, U)g(Z, V) - g(Y, V)S(Z, U) + S(JY, V)g(JZ, U) \\ & - S(JZ, V)g(JY, U) + S(JY, U)g(JZ, V) - g(JY, V)S(JZ, U) = 0. \end{aligned}$$

Now putting $V = \rho$ and $U = \rho$, we get

$$(3.12) \quad 2[S(Y, \rho)g(Z, \rho) - g(Y, \rho)S(Z, \rho) + S(JY, \rho)g(JZ, \rho) - S(JZ, \rho)g(JY, \rho)] = 0.$$

Now using (1.10) in (3.12), we get

$$\delta[A(Z)C(Y) - A(Y)C(Z) + A(JZ)C(JY) - A(JY)C(JZ)] = 0.$$

This implies either $\delta = 0$ or

$$(3.13) \quad A(Z)C(Y) - A(Y)C(Z) = A(JY)C(JZ) - A(JZ)C(JY).$$

If we take $\lambda \neq \frac{r}{(2n+2)}$ and $\delta \neq 0$, then from (1.1) and (1.5), equation (3.13) implies

$$g(Z, \rho) g(Y, \mu) - g(Y, \rho) g(Z, \mu) = g(Y, J\rho) g(Z, J\mu) - g(Z, J\rho) g(Y, J\mu),$$

i.e., $g(Z, \rho) g(Y, \mu) = g(Y, \rho) g(Z, \mu)$ if and only if $g(Y, J\rho) g(Z, J\mu) = g(Z, J\rho) g(Y, J\mu)$. Therefore we can say that the vector fields ρ and μ corresponding to the 1-forms A and C respectively are codirectional if and only if the vector fields $\bar{\rho}$ and $\bar{\mu}$ corresponding to the 1-forms A and C respectively are codirectional.

Thus we conclude:

Theorem 3.2. *In a Bochner flat Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold, if $\frac{r}{(2n+2)}$ is not an eigenvalue of the Ricci operators Q and JQ , and $\delta \neq 0$, then the vector fields ρ and μ corresponding to the 1-forms A and C respectively are codirectional if and only if the vector fields $\bar{\rho}$ and $\bar{\mu}$ corresponding to the 1-forms A and C respectively are codirectional.*

4 Holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold

The holomorphically projective curvature tensor is defined by [22]

$$(4.1) \quad P(X, Y, Z, W) = R(X, Y, Z, W) - \frac{1}{n-2} [S(Y, Z)g(X, W) - S(X, Z)g(Y, W) + S(JX, Z)g(JY, W) - S(JY, Z)g(JX, W)].$$

This tensor has the following properties

$$P(X, Y, Z, W) = -P(Y, X, Z, W), \quad P(JX, JY, Z, W) = P(X, Y, Z, W).$$

Now we introduce the following:

Definition 4.1. An even dimensional Hermitian manifold (M^n, g) is said to be a holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold if the holomorphically projective curvature tensor of the manifold satisfies $P.S = 0$, i.e.,

$$(4.2) \quad (P(X, Y).S)(Z, W) = -S(P(X, Y)Z, W) - S(Z, (P(X, Y)W)) = 0,$$

for all $X, Y, Z, W \in \chi(M^n)$.

If we take a holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold, then from the (1.9) and (4.2), we have

$$(4.3) \quad \begin{aligned} & \alpha[P(X, Y, Z, W) + P(X, Y, W, Z)] \\ & + \beta[A(P(X, Y)Z)A(W) + A(Z)A(P(X, Y)W)] \\ & + \gamma[C(P(X, Y)Z)C(W) + C(Z)C(P(X, Y)W)] \\ & + \delta[A(P(X, Y)Z)C(W) + A(W)C(P(X, Y)Z) \\ & + A(Z)C(P(X, Y)W) + C(Z)A(P(X, Y)W)] \\ & + \eta[D(P(X, Y)Z, W) + D(Z, P(X, Y)W)] = 0. \end{aligned}$$

Now putting $Z = U = \rho$ in (4.3), we have

$$(4.4) \quad (\alpha + \beta)P(X, Y, \rho, \rho) + \delta P(X, Y, \rho, \mu) = 0.$$

Using $Z = W = \rho$ in (4.1), we infer

$$(4.5) \quad P(X, Y, \rho, \rho) = -\frac{\delta}{n-2}[C(Y)A(X) - A(Y)C(X) + C(JX)A(JY) - C(JY)A(JX)].$$

Similarly, putting $Z = \rho$ and $W = \mu$ in (4.1), we get

$$(4.6) \quad P(X, Y, \rho, \mu) = R(X, Y, \rho, \mu) - \frac{(\alpha + \beta)}{n-2}[A(Y)C(X) - C(Y)A(X) + C(JY)A(JX) - C(JX)A(JY)].$$

Using equations (4.5) and (4.6) in (4.4), we get

$$\delta[R(X, Y, \rho, \mu) = 0.$$

This implies that either $\delta = 0$, or $R(X, Y, \rho, \mu) = 0$. If $\delta = 0$, then from equation (1.9), we get the condition of pseudo-generalised quasi-Einstein manifolds. Thus we can conclude:

Theorem 4.1. *A holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold is either a holomorphically projective Ricci semi-symmetric pseudo generalised quasi-Einstein Hermitian manifold or*

$$R(X, Y, \rho, \mu) = 0.$$

Putting $Z = \rho$ and $W = \mu$ in equation (4.3), we get

$$(4.7) \quad \alpha[P(X, Y, \rho, \mu) + P(X, Y, \mu, \rho)] + \beta P(X, Y, \mu, \rho) + \gamma[P(X, Y, \rho, \rho) + P(X, Y, \mu, \mu)] = 0.$$

Again, putting $Z = U = \mu$ in (4.1), we get

$$(4.8) \quad P(X, Y, \mu, \mu) = -\frac{\gamma}{n-2}[A(Y)C(X) - C(Y)A(X) + C(JY)A(JX) - C(JX)A(JY)].$$

Adding equations (4.5) and (4.8), we infer

$$(4.9) \quad P(X, Y, \mu, \mu) + P(X, Y, \rho, \rho) = 0,$$

from (4.7) and (4.9), we have

$$(4.10) \quad \alpha[P(X, Y, \rho, \mu) + P(X, Y, \mu, \rho)] + \beta P(X, Y, \mu, \rho) + \gamma P(X, Y, \rho, \mu) = 0.$$

Now putting $Z = \mu$ and $W = \rho$ in equation (4.1), we yield

$$(4.11) \quad P(X, Y, \mu, \rho) = R(X, Y, \mu, \rho) - \frac{(\alpha + \gamma)}{n-2}[C(Y)A(X) - A(Y)C(X) + C(JX)A(JY) - C(JY)A(JX)].$$

From equations (4.6), (4.10) and (4.11), we have

$$(4.12) \quad (\gamma - \beta)[R(X, Y, \mu, \rho)] = 0.$$

This implies either $\beta = \gamma$, or $R(X, Y, \mu, \rho) = 0$.

Theorem 4.2. *In a holomorphically projective Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold, if $\beta \neq \gamma$ then $R(X, Y, \mu, \rho) = 0$.*

Acknowledgements. The first author is thankful to UGC for financial support in the form of Senior Research Fellowship (Ref. no.: 22/06/2014(I)EU-V).

References

- [1] T. Adati and T. Miyazawa, *On a Riemannian space with recurrent conformal curvature*, Tensor N. S. 18(1967), 348-354.
- [2] A. Bhattacharyya, M. Tarafdar and D. Debnath, *On mixed super quasi-Einstein manifolds*, Differential Geometry-Dynamical Systems, 10(2008), 44-57.
- [3] S. Bochner, *Curvature and Betti numbers II*, Ann. of Math., 50(1949), 77-93.
- [4] M.C. Chaki and R.K. Maity, *On quasi-Einstein manifolds*, Publ. Math. Debrecen, 57(2000), 297-306.
- [5] M.C. Chaki, *On generalized quasi-Einstein manifolds*, Publ. Math. Debrecen, 58(2001), 683-691.
- [6] M.C. Chaki, *On super quasi-Einstein manifold*, Publ. Math. Debrecen, 64(2004), 481-488.
- [7] U.C. De and G.C. Ghosh, *On quasi-Einstein and special quasi-Einstein manifolds*, Proc. of the Conf. of Mathematics and Its Applications, Kuwait University, April 5-7 (2004), 178-191.
- [8] F. Defever, *Ricci-semisymmetric hypersurfaces*, Balkan Journal of Geometry and Its Appl. 5(2000), 81-91.
- [9] P. Debnath and A. Konar, *On quasi-Einstein manifolds and quasi-Einstein spacetimes*, Differ. Geom. Dyn. Syst. 12(2010), 73-82.
- [10] R. Deszcz, *On pseudo-symmetric spaces*, Bull. Soc. Math. Belg. Ser. A 44(1992)1-34.
- [11] S. Guha, *On quasi-Einstein and generalized quasi-Einstein manifolds*, Facta Universitatis, Series Mechanics, Automatic Control and Robotics, 3(2003), 821-842.
- [12] A. Hosseinzadeh and A. Taleshian, *On conformal and quasi-conformal curvature tensors of an $N(k)$ -quasi-Einstein manifold*, Commun. Korean Math. Soc., 27(2012), 317-326.
- [13] S.K. Hui and R.S. Lemence, *On generalized quasi Einstein manifold admitting W_2 -curvature tensor*, Int. Journal of Math. Analysis, 6, 23(2012), 1115 - 1121.
- [14] C. Ozgur and S. Sular, *On $N(k)$ -quasi-Einstein manifolds satisfying certain conditions*, Balkan J. Geom. Appl., 13(2008), 74-79.
- [15] D.G. Prakasha and H. Venkatesha, *Some results on generalized quasi-Einstein manifolds*, Chinese Journal of Mathematics (Hindawi Publishing Corporation), Volume 2014, Article ID 563803 (2014), 5 pages.

- [16] Z.I. Szabo, *Structure theorems on Riemannian spaces satisfying $R(X, Y).R=0$. The local version*, J. Diff. Geom. 17(1982), 531-582.
- [17] A.A. Shaikh, *On pseudo quasi Einstein manifold*, Period. Math. Hungar., 59(2009), 119-146.
- [18] A.A. Shaikh and S.K.Jana, *On pseudo-generalised quasi Einstein manifold*, Tamkang Journal of Mathematics, 39(2008), 9-24.
- [19] A. Taleshian and A.A. Hosseinzadeh, *Investigation of some conditions on $N(k)$ -quasi Einstein manifolds*, Bull. Malays. Math. Sci. Soc., 34(2011), 455-464.
- [20] M.M. Tripathi and J.S Kim, *On $N(k)$ -quasi-Einstein manifolds*, Commun. Korean Math. Soc., 22(3) (2007), 411-417.
- [21] A.G. Walker, *On Ruse's spaces of recurrent curvature*, Proc. London Math. Soc. 52(1950), 36-64.
- [22] K. Yano., *Differential Geometry of Complex and Almost Complex Spaces*, Pergamon Press, New York, 1965.

Authors' addresses:

Brijesh Kumar Gupta, Braj Bhushan Chaturvedi
Department of Pure & Applied Mathematics,
Guru Ghasidas Vishwavidyalaya Bilaspur (C.G.), India.
E-mail: brijeshggv75@gmail.com ; brajbhushan25@gmail.com

Mehraj Ahmad Lone
Department of Mathematics, NIT Srinagar,
Hazratbal Srinagar, India.
E-mail: mehraj.jmi@gmail.com